# Homework 4 Solution PHZ 5156, Computational Physics September 15, 2005

# Part 1

With the proposed solution y(t) the matrix product –ay on the right-hand side of the ODE produces –y. The derivative dy/dt on the left-hand side also produces -y. The two sides are equal, so the proposed y(t) is indeed a solution.

#### **Completed code:**

#Homework 4 #Computational Physics PHZ 5156 September 2005 from scipy import \* from scipy.integrate import odeint import time import Gnuplot,Gnuplot.funcutils from LinearAlgebra import \*

```
def rk4(f,y0,t):
```

#Implements 4th order Runge Kutta, using an external f(y).
#Usage: y=rk4(f,y0,t)
#Input f is the name of the "RHS" function.
#Input y0 is an array that contains the initial conditions.
#Notice that y0 can have arbitrary length.
#Input t is an array of times.
#Output array y has shape len(t) x len(y0) where
#y[n,:] contains y(tn) for all computed times.

return -dot(a,y)

```
def analytic(t):
  #Analytic solution
  y1 = 2.*exp(-t)
  y^2 = -exp(-t)
  return y1,y2
def part2():
                                        This file contains the code for the entire
  # Part (2): rk4 with tiny step
  tau = 0.0001
                                        homework assignment. Separate parts are
  t = arange(0., 6+tau, tau)
                                        solved in separate functions; these are invoked
  y0 = array((2.,-1.))
                                        from the main program.
  start = time.clock()
  y = rk4(ode,y0,t)
  finish = time.clock()
  elapsedb = finish - start
  print "\nPart (2)"
  print "rk4 with tau =",tau,"takes time = ",elapsedb
  print "Final values"
  print "y1 analytic:",y1a[-1]
  print "y1 numeric: ",y[-1,0]
  print "y2 analytic:",y2a[-1]
  print "y2 numeric: ",y[-1,1]
  g=Gnuplot.Gnuplot(debug=0)
  g.title('HW 4 Part (2): Stiff ODE solved by RK4 with tau=0.0001')
  g('set data style lines')
  g1 = Gnuplot.Data(ta,y1a,title='y1 ana')
  g2 = Gnuplot.Data(ta,y2a,title='y2 ana')
  g3 = Gnuplot.Data(t,y[:,0],title='y1 RK4')
  g4 = Gnuplot.Data(t,y[:,1],title='y2 RK4')
  g.plot(g1,g2,g3,g4)
  return
def part3():
  #Part (3): RK4 with tau = 0.01
  tau = 0.01
  t = arange(0.,10*tau, tau)
  y0 = array((2.,-1.))
  y = rk4(ode,y0,t)
  y1,y2 = analytic(t)
  print "\nPart (3)"
  print "Values at first 10 times"
  print "y1 analytic:",y1[0:len(t)]
  print "y1 numeric: ",y[:,0]
  print "y2 analytic:",y2[0:len(t)]
  print "y2 numeric: ",y[:,1]
```

```
return
def part4():
  #Part (4): Eigenvalues
  evalues = eigenvalues(a)
  print "\nPart (4)"
  print "Eigenvalues=\n",evalues
def part5():
  #Part (5): odeint with tau = 0.01
  tau = 0.01
  t = arange(0., 6+tau, tau)
  start = time.clock()
  y0 = array((2.,-1.))
  y = odeint(ode,y0,t)
  finish = time.clock()
  elapsede = finish-start
  print "\nPart (5)"
  print "odeint with tau=0.01 takes time = ",elapsede
  g = Gnuplot.Gnuplot(debug=0)
  g.title('HW 4 Part (5): Stiff ODE solved by odeint with tau=0.01')
  g('set data style lines')
  g1 = Gnuplot.Data(ta,y1a,title='y1 ana')
  g2 = Gnuplot.Data(ta,y2a,title='y2 ana')
  g3 = Gnuplot.Data(t,y[:,0],title='y1 odeint')
  g4 = Gnuplot.Data(t,y[:,1],title='y2 odeint')
  g.plot(g1,g2,g3,g4)
  print "Final values at times:",ta[-1],t[-1]
  print "y1 analytic:",y1a[-1]
  print "y1 numeric: ",y[-1,0]
  print "y2 analytic:",y2a[-1]
  print "y2 numeric: ",y[-1,1]
#Main program
a = array( ((-9998,-19998),(9999,19999)), Float)
print "\n HW4 \n"
#Analytic solution
tau = 0.05
ta = arange(0.0, 6+tau, tau)
y1a, y2a = analytic(ta)
                                        Here the four separate functions are
                                        invoked. In fact I commented out all
part2(); part3()
                                       but one at a time while I was working
part4(); part5()
                                        on this.
```

# Part 2

Executing the RK4 code with tau=0.0001 produces the output

```
Part (2)
rk4 with tau = 0.0001 takes time = 15.84
Final values
y1 analytic: 0.00495750435333
y1 numeric: 0.00495750435333
y2 analytic: -0.00247875217667
y2 numeric: -0.00247875217667
```

This took a very long time to run (nearly 16 seconds) because the step size was so very small. To go from 0 to 6 with a step size of 0.0001 takes 60,000 iterations of the RK4 algorithm. On the other hand the numerical results agree *exactly* with the analytical at the last time step – an amazing accuracy. The plotted results show the same agreement:



## Part 3

Running RK4 with tau=0.01 produces the following output.

```
Values at first 10 times

y1 analytic: [ 2. 1.98009967 1.96039735 1.94089107 1.92157888 1.90245885

1.88352907 1.86478764 1.84623269 1.82786237]

y1 numeric: [ 2.0000000e+00 1.98009967e+00 1.96015930e+00 -9.51417246e+02

-3.81810495e+09 -1.52911324e+16 -6.12394713e+22 -2.45258020e+29

-9.82234088e+35 -3.93375028e+42]

y2 analytic: [-1. -0.99004983 -0.98019867 -0.97044553 -0.96078944 -0.95122942

-0.94176453 -0.93239382 -0.92311635 -0.91393119]

y2 numeric: [ -1.0000000e+00 -9.90049834e-01 -9.79960625e-01 9.52387691e+02

3.81810495e+09 1.52911324e+16 6.12394713e+22 2.45258020e+29

9.82234088e+35 3.93375028e+42]
```

The divergence shows that RK4 is unstable for this ODE with tau=0.01.

#### Part 4

The eigenvalues of matrix *a* are:

Eigenvalues= [ 1.0000000e+00 1.0000000e+04]

This explains what goes wrong in part 3. The RK4 algorithm, like the Euler algorithm, is conditionally stable for this problem. That is, it is only stable for a step size tau less than some threshold value. For Euler the stability condition is tau<2/(maximum eigenvalue), that is, tau<2/10000 (using the result above). I don't know the stability condition for RK4, but can guesstimate that tau needs to be less than some number of order 1/(maximum eigenvalue), that is, tau<O(0.0001). At least it is easy to see the reason for the instability in part 3: tau there is bigger than the RK4 stability threshold.

#### Part 5

Running odeint with tau=0.01 produces the output

Notice that this is stable even for the step size tau=0.01 for which RK4 was unstable. The answers are accurate to about five decimal places. This is less accurate than RK4 with the extremely small step size tau=0.0001, but is quite satisfactory accuracy. And, most important, odeint gave this satisfactory result with a larger step size that enabled it to run much faster – an elapsed time of around 0.01 s. The plotted results also show this good agreement:

